

# MATH 220 - Lecture 9 (09/17/2013)

9.1

## Review

We are going to slow down a bit, as the other sections are a bit behind. We will review some concepts in this lecture.

$$A = \begin{bmatrix} 1 & 2 \end{bmatrix}, \quad x_1 \text{ basic}, \quad x_2 \text{ free}$$

trivial solution to  $A\bar{x} = 0$  is  $\bar{x} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ .

$[1 \ 2 \ | \ 0]$  in reduced echelon form

$$x_1 + 2x_2 = 0 \quad x_2 \text{ free} \quad x_1 = -2s, \quad s \in \mathbb{R}$$

$$\bar{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \end{bmatrix} s, \quad s \in \mathbb{R}.$$

e.g.  $s=2, \quad \bar{x} = \begin{bmatrix} -4 \\ 2 \end{bmatrix} \quad (-4) + 2(2) = 0$

So, pivot in every column of  $A$  means  $A\bar{x} = \bar{0}$  has only the trivial solution.

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Section 1.4 Page 41, Prob 18

$$B = \begin{bmatrix} 1 & 4 & 1 & 2 \\ 0 & 1 & 3 & -4 \\ 0 & 2 & 6 & 7 \\ 2 & 9 & 5 & -7 \end{bmatrix}.$$

Do the columns of  $B$  span  $\mathbb{R}^4$ ?

Every vector in  $\mathbb{R}^4$  can be written as a linear combination of the columns of  $B$  if  $B$  has a pivot in every row.

Equivalently, if  $B$  has a pivot in every row, the span of its columns is (all of)  $\mathbb{R}^4$ .

$$B = \begin{bmatrix} 1 & 4 & 1 & 2 \\ 0 & 1 & 3 & -4 \\ 0 & 2 & 6 & 7 \\ 2 & 9 & 5 & -7 \end{bmatrix} \xrightarrow{R_4 - 2R_1} \begin{bmatrix} 1 & 4 & 1 & 2 \\ 0 & 1 & 3 & -4 \\ 0 & 2 & 6 & 7 \\ 0 & 1 & 3 & -11 \end{bmatrix} \xrightarrow{\begin{matrix} R_3 - 2R_2 \\ R_4 - R_2 \end{matrix}} \begin{bmatrix} 1 & 4 & 1 & 2 \\ 0 & 1 & 3 & -4 \\ 0 & 0 & 0 & 15 \\ 0 & 0 & 0 & -7 \end{bmatrix} \xrightarrow{R_4 + \frac{7}{15}R_3}$$

$$\begin{bmatrix} 1 & 4 & 1 & 2 \\ 0 & 1 & 3 & -4 \\ 0 & 0 & 0 & 15 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Since every row does not have a pivot,  $\text{Span}\{\text{columns of } B\} \neq \mathbb{R}^4$ .

B has 3 pivots.

Q: Do columns of B span  $\mathbb{R}^3$ ?

$\mathbb{R}^3$

Reward: Can you write every vector in  $\mathbb{R}^3$  as a combination of columns of B?

No! As columns of B sit in  $\mathbb{R}^4$ , and not in  $\mathbb{R}^3$ .

Every column of B has four entries, while any vector  $\vec{u}$  in  $\mathbb{R}^3$  has three entries. So, we cannot write  $\vec{u}$  as  $b_1x_1 + b_2x_2 + b_3x_3 + b_4x_4$ .

Similarly, if B had only 2 pivots, its columns would still not span  $\mathbb{R}^2$ .

Prob 24, pg 41 (T/F)

- 24. a. Every matrix equation  $A\mathbf{x} = \mathbf{b}$  corresponds to a vector equation with the same solution set.
- b. If the equation  $A\mathbf{x} = \mathbf{b}$  is consistent, then  $\mathbf{b}$  is in the set spanned by the columns of  $A$ .
- c. Any linear combination of vectors can always be written in the form  $A\mathbf{x}$  for a suitable matrix  $A$  and vector  $\mathbf{x}$ .
- d. If the coefficient matrix  $A$  has a pivot position in every row, then the equation  $A\mathbf{x} = \mathbf{b}$  is inconsistent.
- e. The solution set of a linear system whose augmented matrix is  $[\mathbf{a}_1 \ \mathbf{a}_2 \ \mathbf{a}_3 \ \mathbf{b}]$  is the same as the solution set of  $A\mathbf{x} = \mathbf{b}$ , if  $A = [\mathbf{a}_1 \ \mathbf{a}_2 \ \mathbf{a}_3]$ .
- f. If  $A$  is an  $m \times n$  matrix whose columns do not span  $\mathbb{R}^m$ , then the equation  $A\mathbf{x} = \mathbf{b}$  is consistent for every  $\mathbf{b}$  in  $\mathbb{R}^m$ .

(a) T. If  $A = [\bar{a}_1 \ \bar{a}_2 \ \dots \ \bar{a}_n]$ , then  $A\bar{\mathbf{x}} = \bar{\mathbf{b}}$  corresponds to the vector equation  $\bar{a}_1 x_1 + \bar{a}_2 x_2 + \dots + \bar{a}_n x_n = \bar{\mathbf{b}}$ .

(b) T. If  $\bar{\mathbf{x}}$  is a solution, we can write  $\bar{\mathbf{b}} = \bar{a}_1 x_1 + \dots + \bar{a}_n x_n$ , where  $\bar{a}_i$ 's are the columns of  $A$ .

(c) T. Same reason as above.

(d) F. Pivot in every row means  $A\bar{\mathbf{x}} = \bar{\mathbf{b}}$  is consistent for every  $\bar{\mathbf{b}}$ .

(e) T. From the definition.

(f) F. If columns of  $A$  span  $\mathbb{R}^m$ , then  $A\bar{\mathbf{x}} = \bar{\mathbf{b}}$  has a solution for every  $\bar{\mathbf{b}} \in \mathbb{R}^m$ .

Section 1.5 pg 48, Prob 26.

A is the  $3 \times 3$  zero matrix. Describe solutions of  $A\bar{x} = \bar{0}$ .

$$A = \begin{matrix} & \begin{matrix} x_1 & x_2 & x_3 \end{matrix} \\ \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} & \text{is in reduced echelon form.} \\ & x_1, x_2, x_3 \text{ are all free variables.} \end{matrix}$$

$$\bar{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} s + \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} t + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} u, \quad s, t, u \in \mathbb{R}.$$

So, the solution set is all of  $\mathbb{R}^3$ .

Prob 27 (pg 48)

$A\bar{x} = \bar{b}$  is consistent. Explain why it has a unique solution precisely when  $A\bar{x} = \bar{0}$  has only the trivial solution.

$A\bar{x} = \bar{0}$  has only the trivial solution if A has no free variables.

We could use the same set of EROs that take A to echelon form, and apply them to  $[A|\bar{b}]$ . Hence, the system  $A\bar{x} = \bar{b}$  has free variables if and only if A has free variables.

# A similar question

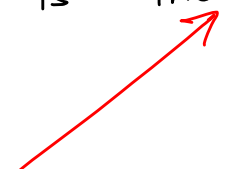
Let  $A\bar{x} = \bar{0}$  have nontrivial solutions. Can you guarantee that  $A\bar{x} = \bar{b}$  always has infinitely many solutions?

The statement holds as long as  $A\bar{x} = \bar{b}$  is consistent.

$A = \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix}$   $x_2$  free So  $A\bar{x} = \bar{0}$  has nontrivial solutions.

But  $A\bar{x} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$  is inconsistent!

$\begin{bmatrix} 1 & 2 & | & 1 \\ 0 & 0 & | & 1 \end{bmatrix}$



When answering True/False problems, try to provide the simplest counter examples when possible, as above.