

MATH 220 - Lecture 24 (11/07/2013)

Computer project - due Thursday, Dec 5.

One of the main goals of the computer project is to make yourselves familiar with MATLAB. You have access to MATLAB through the web portal at <http://my.math.wsu.edu>.

We present the session (equivalent 😊!) in MATLAB seen during the lecture to the right. 

```
%% commands from the MATLAB session in Lecture 24 on Thursday,  
%% November 7, 2013.
```

```
%% To illustrate row reduction, we used Problem 5 from Page 157 of the  
%% book, which was solved in Lecture 23. In this problem, 3-vectors  
%% b1, b2, and x are given, and we are asked to the B-coordinates of x  
%% in the basis B = {b1,b2}.
```

```
%% You should check out some of the MATLAB tutorials listed in the  
%% Computer Project description.
```

```
%% We can use the % sign to add comments - MATLAB ignores anything  
%% written in a line following a % sign. Extra comments are added in  
%% between the MATLAB commands here to illustrate.
```

```
>> b1 = [1  
4  
-3]  
b1 =  
1  
4  
-3
```

```
% A' (prime) transposes a matrix or a vector when added to its  
% end. Also, if you do not want MATLAB to display the output of a  
% command, end the same with a ; (semi-colon).
```

```
>> b2 = [-2 -7 5];
```

```
>> x = [2 9 -7];  
>> AugMtx = [b1 b2 x]  
AugMtx =  
1 -2 2  
4 -7 9  
-3 5 -7
```

```
% Error messages in MATLAB - usually point out where the source of  
% error is. Or, at least tell you from where things go wrong.
```

```
>> AugMtx = [b1 b2 x]  
??? Error using ==> horzcat CAT  
arguments dimensions are not consistent.
```

```
% In the above command, x' is 1 x 3, while b1 and b2 are both  
% 3 x 1. Hence the dimensions do not match.
```

```
>> AugMtx = [b1 b2 x];
```

```
>> rref(AugMtx)  
ans =  
1 0 4  
0 1 1  
0 0 0
```

You need to be aware of at least the basic commands related to matrix/vector operations in MATLAB.

Several computations (or, implemented) already in MATLAB. In particular, `rref` (reduced row echelon form), `det` (determinant), `rank` (rank), `inv` (inverse), are quite useful.

```
>> help rref
RREF Reduced row echelon form.
R = RREF(A) produces the reduced row echelon form of A.

[R,jb] = RREF(A) also returns a vector, jb, so that:
r = length(jb) is this algorithm's idea of the rank of A,
x(jb) are the bound variables in a linear system, Ax = b,
A(:,jb) is a basis for the range of A,
R(1:r,jb) is the r-by-r identity matrix.

[R,jb] = RREF(A,TOL) uses the given tolerance in the rank tests.

Roundoff errors may cause this algorithm to compute a different
value for the rank than RANK, ORTH and NULL.

Class support for input A:
float: double, single

See also RANK, ORTH, NULL, QR, SVD.

% You could ask MATLAB to print rational numbers rather than decimal
% numbers. Here is an example.

>> rref([b1 b2 x/3])
ans =
    1.0000     0    1.3333
         0    1.0000    0.3333
         0     0         0

>> format rat

>> rref([b1 b2 x/3])
ans =
     1         0         4/3
     0         1         1/3
     0         0         0

% Following are the two determinant calculations we did class by
% hand. As illustrated here, you could verify any determinant
% calculations you are doing in the homework using MATLAB!

>> det([0 5 1; 4 -3 0; 2 4 1])
ans =
     2
>> det([1 -2 5 2; 0 0 3 0; 2 -6 -7 5; 5 0 4 4])
ans =
    -6
```

We will revisit the actual problems described in the project once we introduce eigenvalues and eigenvectors.

Determinant of $A \in \mathbb{R}^{n \times n}$ by expanding along Row-1

As illustrated in the previous lecture, we could compute the determinant of any square matrix by expanding along its Row-1.

In general, for $A \in \mathbb{R}^{n \times n}$ with

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix}$$

$$\det A = a_{11} \det A_{11} - a_{12} \det A_{12} + a_{13} \det A_{13} - \dots + (-1)^{n+1} a_{1n} \det A_{1n},$$

where A_{ij} is the $(n-1) \times (n-1)$ matrix obtained by removing Row 1 and Column j of A .

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Compute the determinant by expanding along Row 1.

$$2. \begin{vmatrix} 0 & 5 & 1 \\ 4 & -3 & 0 \\ 2 & 4 & 1 \end{vmatrix} \quad \leftarrow \text{determinant}$$

$[] \leftarrow$ notation for a matrix
 $| | \leftarrow$ determinant of the matrix written inside

$$= 0 \cdot \begin{vmatrix} -3 & 0 \\ 4 & 1 \end{vmatrix} - 5 \begin{vmatrix} 4 & 0 \\ 2 & 1 \end{vmatrix} + 1 \begin{vmatrix} 4 & -3 \\ 2 & 4 \end{vmatrix}$$

$$= 0(-3 \times 1 - 4 \times 0) - 5(4 \times 1 - 2 \times 0) + 1(4 \times 4 - 2 \times 3)$$

$$= 0 - 20 + 22 = 2.$$

In fact we can expand along **any row** or **any column** to evaluate the determinant.

The result is given as Theorem 1 in the book.

Define $C_{ij} = (-1)^{i+j} \det A_{ij}$
 → cofactor
 → remove row i column j from matrix A

The (i,j) -th cofactor of a matrix is the determinant of the submatrix obtained by removing Row i and Column j from the original matrix, multiplied by the appropriate sign that depends on $i+j$, i.e., by $(-1)^{i+j}$.

Expanding along column j :

$$\det A = a_{1j}C_{1j} + a_{2j}C_{2j} + \dots + a_{nj}C_{nj}.$$

Expanding along Row i :

$$\det A = a_{i1}C_{i1} + a_{i2}C_{i2} + \dots + a_{in}C_{in}.$$

Notice that the alternating \pm signs are included in the cofactor values.

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Compute the determinants in Exercises 9–14 by cofactor expansions. At each step, choose a row or column that involves the least amount of computation.

$$10. \begin{vmatrix} 1 & -2 & 5 & 2 \\ 0 & 0 & 3 & 0 \\ 2 & -6 & -7 & 5 \\ 5 & 0 & 4 & 4 \end{vmatrix}$$

We look for a row or a column with lots of zeros, and expand along that row/column. We repeat this idea for the 3×3 determinant in the next step.

$$= 3 \cdot (-1)^{(2+3)} \begin{vmatrix} 1 & -2 & 2 \\ 2 & -6 & 5 \\ 5 & 0 & 4 \end{vmatrix} =$$

$$= -3 \left((-2) \cdot (-1)^{(1+2)} \begin{vmatrix} 2 & 5 \\ 5 & 4 \end{vmatrix} + (-6) \cdot (-1)^{(2+2)} \begin{vmatrix} 1 & 2 \\ 5 & 4 \end{vmatrix} \right)$$

$$= -3 \left(2(8-25) + (-6)(4-10) \right)$$

$$= -3(-34+36) = -6.$$