



$$\xrightarrow{R_2 - R_1} \begin{pmatrix} 0 & 1 & 2 & 0 \\ 1 & 0 & 3 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{R_{1,2}, R_{3,4}} \begin{pmatrix} 1 & 0 & 3 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \Rightarrow x_3 \text{ free.} \quad (2)$$

It follows, the solution set of the above homogeneous system is the set of vectors mapped to  $\vec{0}$ :

Since  $\vec{x} = x_3 \cdot \begin{pmatrix} -3 \\ -2 \\ 1 \\ 0 \end{pmatrix}$  determines the solution set,

all multiples of  $\vec{v} = \begin{pmatrix} -3 \\ -2 \\ 1 \\ 0 \end{pmatrix}$  are mapped by  $A$  to  $\vec{0}$ .

12. Solve:

$$\begin{pmatrix} 1 & 3 & 9 & 2 & | & -1 \\ 1 & 0 & 3 & -4 & | & 3 \\ 0 & 1 & 2 & 3 & | & -1 \\ -2 & 3 & 0 & 5 & | & 4 \end{pmatrix} \xrightarrow{R_1 - R_2} \begin{pmatrix} 0 & 3 & 6 & 6 & | & -4 \\ 1 & 0 & 3 & -4 & | & 3 \\ 0 & 1 & 2 & 3 & | & -1 \\ -2 & 3 & 0 & 5 & | & 4 \end{pmatrix} \xrightarrow{R_4 + 2R_2}$$

$$\rightarrow \begin{pmatrix} 0 & 3 & 6 & 6 & | & -4 \\ 1 & 0 & 3 & -4 & | & 3 \\ 0 & 1 & 2 & 3 & | & -1 \\ 0 & 3 & 6 & -3 & | & 14 \end{pmatrix} \xrightarrow{R_4 - R_1} \begin{pmatrix} 0 & 3 & 6 & 6 & | & -4 \\ 1 & 0 & 3 & -4 & | & 3 \\ 0 & 1 & 2 & 3 & | & -1 \\ 0 & 0 & 0 & -9 & | & 14 \end{pmatrix} \xrightarrow{R_1 - 3R_3}$$

$$\rightarrow \begin{pmatrix} 0 & 0 & 0 & -3 & | & -1 \\ 1 & 0 & 3 & -4 & | & 3 \\ 0 & 1 & 2 & 3 & | & -1 \\ 0 & 0 & 0 & -9 & | & 14 \end{pmatrix} \xrightarrow{R_1 - \frac{1}{3}R_4} \begin{pmatrix} 0 & 0 & 0 & 0 & | & -13/3 \\ 1 & 0 & 3 & -4 & | & 3 \\ 0 & 1 & 2 & 3 & | & -1 \\ 0 & 0 & 0 & -9 & | & 14 \end{pmatrix} \rightarrow$$

$\Rightarrow$  inconsistent  $\Rightarrow b \notin \mathcal{R}(A)$ .

(19)

We have:

$$Te_1 = y_1 = \begin{pmatrix} 2 \\ 5 \end{pmatrix}$$

$$Te_2 = y_2 = \begin{pmatrix} -1 \\ 6 \end{pmatrix}$$

Since  $T$  is linear, it is determined by a matrix: ③

$$Tx = Ax.$$

$$\text{Let } A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}. \quad \text{Then } \begin{pmatrix} a \\ c \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ 5 \end{pmatrix} \Rightarrow$$

$$\Rightarrow \begin{matrix} a = 2 \\ c = 5 \end{matrix}, \quad \begin{pmatrix} b \\ d \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} -1 \\ 6 \end{pmatrix} \Rightarrow \begin{matrix} b = -1 \\ d = 6 \end{matrix}.$$

$$\text{It follows, } A = \begin{pmatrix} 2 & -1 \\ 5 & 6 \end{pmatrix}.$$

The image of  $\begin{pmatrix} 5 \\ -3 \end{pmatrix}$  under  $A$  is:

$$A \begin{pmatrix} 5 \\ -3 \end{pmatrix} = \begin{pmatrix} 2 & -1 \\ 5 & 6 \end{pmatrix} \begin{pmatrix} 5 \\ -3 \end{pmatrix} = \begin{pmatrix} 13 \\ 7 \end{pmatrix}.$$

Similarly,

$$\begin{pmatrix} 2 & -1 \\ 5 & 6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 2x_1 - x_2 \\ 5x_1 + 6x_2 \end{pmatrix}.$$

(24)

a. false: see paragraph preceding example 2.

(5)

b. true: see theorem 10

c. true: see table 1

d. false: see definition of one-to-one. Any function from  $\mathbb{R}^n$  to  $\mathbb{R}^m$  maps a vector onto a single (unique) vector.

e. true: see the solutions of example 5.

19. ~~Not~~ Not one-to-one, but maps  $\mathbb{R}^3$  onto  $\mathbb{R}^2$ .