

## Calculus and Optimization III

We now have a procedure for finding the stationary points of a known function  $f(x)$  of one variable! Given an initial guess  $x_0$ , we find a sequence of approximations

$$x_{k+1} = x_k - \frac{f'(x_k)}{f''(x_k)}, \quad k = 0, 1, 2, \dots$$

which hopefully converge to a stationary point of  $f$ .

Now let's see if we can extend these ideas to find the stationary points of a function of two variables  $f(x, y)$ .

1. Create a local approximation of  $f$  at given point  $(x, y)$ :

$$f(x + a_x, y + a_y) \approx f(x, y) + ??$$

2. Could we use this approximation to find the roots of the function  $f(x, y)$ ?
3. Modify your result and develop a procedure for finding a stationary point of  $f(x, y)$ .
4. Use your iterative procedure to find a stationary point of the function

$$f(x, y) = (e^x - x)(e^y - 2y)$$

with initial guess  $(x, y)_0 = (1, 1)$ .

$$(1) \quad f(x+a_x, y+a_y) \approx f(x, y) + a_x \frac{\partial f}{\partial x}(x, y) + a_y \frac{\partial f}{\partial y}(x, y) \\ = f(x, y) + \mathbf{a}^T \nabla f(x, y)$$

local linear approximation in 2-variables.

$\mathbf{a} = \begin{bmatrix} a_x \\ a_y \end{bmatrix}$  is a direction or step vector.

$\nabla f(x, y) = \begin{bmatrix} \partial f / \partial x \\ \partial f / \partial y \end{bmatrix}$  is the gradient vector.

(2) Suppose we wish to find locations where  $f=0$  starting from point  $(x,y)$ . We would need to find a step vector  $a$  such that

$$0 = f(x+a_x, y+a_y) \approx f(x,y) + a^T \nabla f(x,y).$$

This is one equation in 2 unknowns ( $a_x$  and  $a_y$ ). The solution set is the level line of  $f=0$  in the linear approximation.

(3) Take the gradient of the approximation in (1):

$$\nabla f(x+a_x, y+a_y) \approx \nabla f(x,y) + \nabla (a^T \nabla f(x,y))$$

~~$$\nabla f(x,y) + \begin{bmatrix} \frac{\partial}{\partial x} a^T \nabla f(x,y) \\ \frac{\partial}{\partial y} a^T \nabla f(x,y) \end{bmatrix}$$~~

$$= \nabla f(x,y) + \nabla \left[ a_x \frac{\partial f}{\partial x}(x,y) + a_y \frac{\partial f}{\partial y}(x,y) \right]$$

$$= \nabla f(x,y) + \begin{bmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{bmatrix} \begin{bmatrix} a_x \\ a_y \end{bmatrix}$$

$$= \nabla f(x,y) + \nabla^2 f(x,y) a$$

So, to move a step  $a$  so that  $\nabla f(x+a_x, y+a_y) = 0$ :

$$a = -(\nabla^2 f)^{-1} \nabla f$$

$$\text{And let } a = x_{k+1} - x_k \Rightarrow \boxed{x_{k+1} = x_k - (\nabla^2 f)^{-1} \nabla f}$$

(4) Suppose  $f(x,y) = (e^x - x)(e^y - 2y)$ .

$$\nabla f = \begin{bmatrix} (e^x - 1)(e^y - 2y) \\ (e^x - x)(e^y - 2) \end{bmatrix}$$

$$\nabla^2 f = \begin{bmatrix} e^x(e^y - 2y) & (e^x - 1)(e^y - 2) \\ (e^x - 1)(e^y - 2) & (e^x - x)e^y \end{bmatrix}$$

(a) Start with  $(x_0, y_0) = (1, 1)$ .

$$\nabla f \approx \begin{bmatrix} 1.2342 \\ 1.2342 \end{bmatrix} \quad \nabla^2 f \approx \begin{bmatrix} 1.9525 & 1.2342 \\ 1.2342 & 4.6708 \end{bmatrix}$$

$$(x_1, y_1) = \begin{bmatrix} 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 1.9525 & 1.2342 \\ 1.2342 & 4.6708 \end{bmatrix}^{-1} \begin{bmatrix} 1.2342 \\ 1.2342 \end{bmatrix}$$

$$(x_1, y_1) = \begin{bmatrix} 0.44165 \\ 0.88330 \end{bmatrix}$$

(b) continuing ...

$$(x_2, y_2) = \begin{bmatrix} 0.11792 \\ 0.73808 \end{bmatrix} \quad \nabla f(x_2, y_2) = \begin{bmatrix} 0.36218 \\ 0.46644 \end{bmatrix}$$

$$(x_3, y_3) = \begin{bmatrix} 0.00741 \\ 0.69475 \end{bmatrix} \quad \nabla f(x_3, y_3) = \begin{bmatrix} 0.07706 \\ 0.09259 \end{bmatrix}$$

$$(x_4, y_4) = \begin{bmatrix} 0.00003 \\ 0.69315 \end{bmatrix} \quad \nabla f(x_4, y_4) = \begin{bmatrix} 0.00456 \\ 0.00320 \end{bmatrix}$$

Notice that  $\nabla f$  appears to be converging to  $\nabla f = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ .

We can solve directly for the location of any stationary points. It is reasonably straightforward to show that the only stationary point is at  $(x, y) = (0, \ln 2)$  which is very close to our 4<sup>th</sup> approximation. Evaluation of the Hessian matrix will show that this point is a local minimizer of  $f(x, y)$ .

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How would we terminate our iterative procedure in part (3)?

Two typical tests are to stop if either of the following occur:

(a)  $\|x_{k+1} - x_k\| < \epsilon$

(b)  $\|\nabla f(x_k)\| < \delta$

where  $\epsilon$  and  $\delta$  are user-defined values.

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The iterative procedure can fail to reach a stationary point.

(i) No stationary point may exist

(ii) sequence of  $\{x_k\}$  may not converge

(iii)  $\nabla^2 f$  may not be invertible, or nearly so.