

# ROMBERG INTEGRATION

## Background :

for smooth  $f(x)$ , with  $I(f) = \int_a^b f(x)dx$ , using series,

- Trapezoidal rule  $T_n(f)$  has error expansion

$$I(f) = T_n(f) + c_1h^2 + c_2h^4 + c_3h^6 + \dots$$

for constants  $c_1, c_2, \dots$  independent of  $h$ .

- Midpoint rule  $M_n(f)$  has error expansion

$$I(f) = M_n(f) + d_1h^2 + d_2h^4 + d_3h^6 + \dots$$

for constants  $d_1, d_2, \dots$  independent of  $h$ .

**Extrapolation:** Richardson extrapolation can be used

- **Romberg Integration:** let  $R_{1,1} = T_1(f)$ ,  $h_k = \frac{b-a}{2^{k-1}}$ ,

$$R_{k,1} = \frac{1}{2} \left[ R_{k-1,1} + h_{k-1} \sum_{i=1}^{2^{k-2}} f(a + (2i-1)h_k) \right] \equiv T_{2^{k-1}}(f), \quad k = 2, 3, \dots$$

# NUMERICAL INTEGRATION CONT.

Extrapolation formulas

$$R_{k,2} = R_{k,1} + (R_{k,1} - R_{k-1,1})/(4 - 1), \quad k = 2, 3, \dots$$

⋮

$$R_{k,j} = R_{k,j-1} + (R_{k,j-1} - R_{k-1,j-1})/(4^{j-1} - 1), \quad k = j, j+1, \dots$$

- Romberg Integration Table: computed row by row

$O(h^2)$	$O(h^4)$	$O(h^6)$	$O(h^8)$	$O(h^{10})$	← Errors
$R_{1,1} = T_1(h)$					
$R_{2,1} = T_2(h)$	$R_{2,2}$				
$R_{3,1} = T_4(h)$	$R_{3,2}$	$R_{3,3}$			
$R_{4,1} = T_8(h)$	$R_{4,2}$	$R_{4,3}$	$R_{4,4}$		
$R_{5,1} = T_{16}(h)$	$R_{5,2}$	$R_{5,3}$	$R_{5,4}$	$R_{5,5}$	
⋮	⋮	⋮	⋮	⋮	⋮

Note:  $R_{k,2} = S_{2^{k-1}}(f)$ , Simpsons' rule;  
 but could also use  $R_{k,1} = M_{2^{k-1}}(f)$ .

# NUMERICAL INTEGRATION CONT.

## Romberg Examples :

- $\int_{-.5}^0 x \ln(x + 1) dx = 0.0525698072900205.$

Romberg Table

.0866434				
.0613018	.0528546			
.0547688	.0525911	.052573503		
.0531206	.0525712	.052569893	.052569836	
.0527076	.0525699	.052569809	.052569808	.052569807

- $\int_0^1 e^{-x^2} dx = 0.746824132812427.$

Romberg Table

.6839397				
.7313703	.7471804			
.7429841	.7468554	.746833710		
.7458656	.7468261	.746824170	.746824018	
.7465846	.7468243	.746824133	.746824133	.746824133

- $\int_{-1}^1 \sin(1 + e^{3x}) dx = 2.50080911033617.$

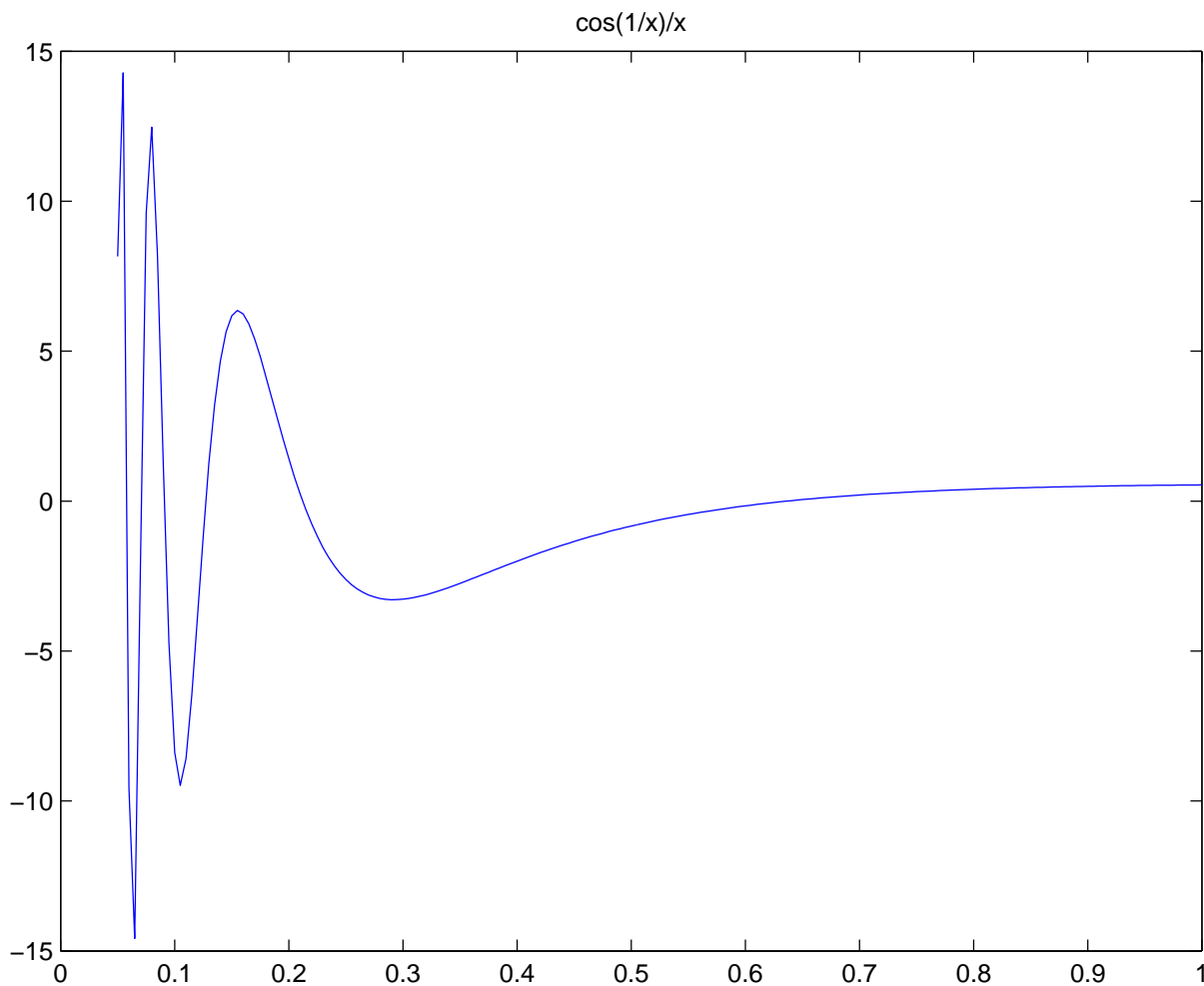
Romberg Table

2.99424					
3.33859	3.45337				
2.29318	1.94471	1.84414			
2.48454	2.54832	2.58856	2.60038		
2.66899	2.73048	2.74262	2.74507	2.74564	
2.51149	2.45899	2.44089	2.43610	2.43488	2.43458
2.50257	2.49959	2.50230	2.50327	2.50354	2.50360
2.50122	2.50077	2.50085	2.50082	2.50081	2.50081

# ADAPTIVE NUMERICAL INTEGRATION

## Adaptive Numerical Integration Background

- Motivation: some numerical integration problems involve integrands with varying smoothness in different parts of integration interval  $[a, b]$ ; efficient computation of  $I(f)$  requires the total number of integrand evaluations to be minimized.



Romberg method for  $\int_{.05}^1 \cos(1/x)/x dx \approx -.29298$   
requires 1025  $f$  values.

- Main Idea: subdivide integration interval  $[a, b]$  nonuniformly, adaptively concentrating work in subintervals where integrand has more variation.

# ADAPTIVE NUMERICAL INTEGRATION

## Local Adaptive Integration, Basic Algorithm

1. input error tolerance  $\epsilon$ ,  $[a, b]$ ,  $f(x)$
2. use integration rule  $R(f, a, b)$ , with error estimate  $E$
3. if  $E > \epsilon$ , apply algorithm to  $f(x)$   
on  $[a, \frac{a+b}{2}]$  and  $[\frac{a+b}{2}, b]$  with error tolerances  $\epsilon/2$ ;  
and return sum of results for two halves  
otherwise, return  $R(f, a, b)$

Produces “tree” of subintervals, results at each tree leaf.

# ADAPTIVE NUMERICAL INTEGRATION

Local Adaptive Algorithm as recursive function Int

Int( $f, a, b, \epsilon$ )

    compute  $R(f, a, b)$  and  $E(f, a, b)$ ;

    if  $E(f, a, b) < \epsilon$ , return  $R(f, a, b)$ ,

    else, return  $\text{Int}(f, a, \frac{a+b}{2}, \frac{\epsilon}{2}) + \text{Int}(f, \frac{a+b}{2}, b, \frac{\epsilon}{2})$ ;

end Int.

Matlab Adaptive quadrature with Simpson's rule:

```
function I = adaptr( a, b, f, ep )
```

```
%  
% Estimates integral of f(x) over [a,b] with  
% estimated accuracy < ep, using recursive  
% adaptive integration based on Simpson's rule.  
% Example:  
% disp( adaptr( -1,1,@(x)1+sin(exp(3*x)),5e-5 ) )  
%  
    I = adint( f, a, b, ep, f(a), f((a+b)/2), f(b) );  
end  
% end adaptr  
function I = adint( f, a, b, ep, fa, fm, fb ),  
    h = (b-a)/2; m = (a+b)/2;  
    fl = f((a+m)/2); L = h*(fa+4*fl+fm)/6; % left  
    fr = f((m+b)/2); R = h*(fm+4*fr+fb)/6; % right  
    er = ( L + R - h*(fa+4*fm+fb)/3 )/15; % error  
    if abs(er) < ep, I = L + R + er;  
    else,  
        I = adint( f, a,m,ep/2, fa,fl,fm ) ...  
            + adint( f, m,b,ep/2, fm,fr,fb );  
    end  
% end adint
```

# ADAPTIVE NUMERICAL INTEGRATION

## Basic Integration Rule with Error Estimate

- Use Trapezoidal Rule on  $[a, b]$ ,  $[a, \frac{a+b}{2}]$ ,  $[\frac{a+b}{2}, b]$ .

$$|I(f) - T(a, \frac{a+b}{2}) - T(\frac{a+b}{2}, b)| \approx \frac{1}{3} |T(a, b) - T(a, \frac{a+b}{2}) - T(\frac{a+b}{2}, b)|.$$

- Use Simpson's Rule on  $[a, b]$ ,  $[a, \frac{a+b}{2}]$ ,  $[\frac{a+b}{2}, b]$ .

$$|I(f) - S(a, \frac{a+b}{2}) - S(\frac{a+b}{2}, b)| \approx \frac{1}{15} |S(a, b) - S(a, \frac{a+b}{2}) - S(\frac{a+b}{2}, b)|.$$

# ADAPTIVE NUMERICAL INTEGRATION

## NonRecursive Adaptive Integration Algorithm :

uses list of results, and reuses  $f$ 's

- *input* error tolerance  $\epsilon$ ,  $[a, b]$ ,  $f(x)$
- *initialize*  
set  $I = 0$ ,  $k = 1$ ,  $a_1 = a$ ,  $h_1 = \frac{b-a}{2}$ ,  
 $fa_1 = f(a)$ ,  $fm_1 = f(a + h_1)$ ,  $fb_1 = f(b)$ ,  
 $S_1 = \frac{h_1}{3}(fa_1 + 4fm_1 + fb_1)$ .
- while  $k > 0$ ,                    *subdivide last interval from list*  
  set  $h_k = h_k/2$ ,  $l = f(a_k + h_k)$ ,  $r = f(a_k + 3h_k)$ ;  
   $L = \frac{h_k}{3}(fa_k + 4l + fm_k)$ ,  $R = \frac{h_k}{3}(fm_k + 4r + fb_k)$ ;  
  if  $|S_k - L - R|/15 < 2\epsilon h_k/(b-a)$ ,            *check error*  
  set  $I = I + L + R + \frac{L+R-S_k}{15}$ ,  $k = k-1$ ;            *save or*  
  else                                *update list with new subintervals*  
  set  $S_{k+1} = R$ ,  $a_{k+1} = a_k + 2h_k$ ,  $h_{k+1} = h_k$ ,    *right*  
   $fa_{k+1} = fm_k$ ,  $fm_{k+1} = r$ ,  $fb_{k+1} = fb_k$ ;  
  set  $S_k = L$ ,  $fb_k = fm_k$ ,  $fm_k = l$ ;                    *left*  
  set  $k = k+1$ ;  
  endif  
  endwhile
- *return*  $I \approx \int_a^b f(x)dx$ .



# ADAPTIVE NUMERICAL INTEGRATION

**Example**  $I(f) = \int_{.05}^1 \cos(1/x)/x \, dx, \epsilon = 10^{-4}$ .

k	I	f's / Subinterval list
1	0.98237602	3
	0.05	1
2	-0.34307544	5
	0.05	0.525
	0.525	1
3	-0.33945425	7
	0.05	0.525
	0.525	0.7625
	0.7625	1
2	-0.33940061	9
	0.05	0.525
	0.525	0.7625
3	-0.33920396	11
	0.05	0.525
	0.525	0.64375
	0.64375	0.7625
2	-0.33919885	13
	0.05	0.525
	0.525	0.64375
1	-0.33919213	15
	0.05	0.525
2	0.71815553	17
	0.05	0.2875
	0.2875	0.525

...

k	I	f's / Subinterval list
1	-0.53523399	91
	0.05	0.079687
2	-0.30308683	93
	0.05	0.064844
	0.064844	0.079688
3	-0.30805689	95
	0.05	0.064844
	0.064844	0.072266
	0.072266	0.079687
4	-0.30815647	97
	0.05	0.064844
	0.064844	0.072266
	0.072266	0.075977
	0.075977	0.079687

...

	0.05	0.051855
	0.051855	0.052783
1	-0.29297842	147
	0.05	0.051855
2	-0.29298195	149
	0.05	0.050928
	0.050928	0.051855
1	-0.29298206	151
	0.05	0.050928
0	-0.29298219	153

# Graphs of $f(x)$ for different numbers of function values

