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On Two-Phase Stefan Problem Arising from a Microwave Heating Process

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Abstract: In this paper we study a free boundary problem modeling a phase-change process by using microwave heating technique. The mathematical model consists of Maxwell's equations coupled with nonlinear heat conduction with a phase-change. The enthalpy form is used to characterize the phase-change process in the model. It is shown that the problem has a global solution.

Key Words and Phases: Microwave heating, phase-change, global existence.

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1. Introduction

Suppose that a material with solid and liquid phases occupies a bounded domain $\Omega \subset R^3$ with C^1 -boundary $\partial\Omega$. If we heat up the material by using intense microwaves from the boundary $\partial\Omega$, the solid phase of the material will begin to melt.

To describe the above physical process, we introduce the electric and magnetic fields $\mathbf{E}(x, t)$ and $\mathbf{H}(x, t)$, respectively, in Ω . Hereafter, a bold letter represents a vector or vector function in three-space dimensions. Then $\mathbf{E}(x, t)$ and $\mathbf{H}(x, t)$ satisfy the following well-known Maxwell equations (see [9]):

$$\varepsilon \mathbf{E}_t + \sigma \mathbf{E} = \nabla \times \mathbf{H}, \quad (x, t) \in Q_T, \quad (1.1)$$

$$\mu \mathbf{H}_t + \nabla \times \mathbf{H} = 0, \quad (x, t) \in Q_T, \quad (1.2)$$

where $Q_T = \Omega \times (0, T]$ and $\mathbf{J}(x, t) = \sigma \mathbf{E}$ is used by Ohm's law, ε, μ and σ are the electric permittivity, magnetic permeability and the electric conductivity, respectively.

Let $u(x, t)$ be the temperature in Q_T . During the heating process, the local density of heat source generated by microwaves is equal to $\mathbf{E} \cdot \mathbf{J} = \sigma(x, u)|\mathbf{E}|^2$, where the electric conductivity $\sigma = \sigma(x, u)$ typically depends on u such as (see [12, 13])

$$\sigma(x, u) = \frac{a(x)}{b(x) + c(x)u}, \text{ or } \sigma(x, u) = a(x)e^{-b(x)u},$$

where $a(x), b(x)$ and $c(x)$ are positive functions. It also may have a jump discontinuity for the temperature changing from solid phase to liquid phase:

$$\sigma(x, u) = \begin{cases} \sigma_l(x, u), & \text{if } u(x, t) < m, \\ \sigma_s(x, u), & \text{if } u(x, t) > m, \end{cases}$$

where the subscript l or s represents the function in liquid or solid phase and m is the melting temperature.

By using the enthalpy method, the temperature $u(x, t)$ satisfies the following heat equation in the weak sense (see [4, 5] and also Remark 1.1 below):

$$A(u)_t - \nabla[k(x, u)\nabla u] = \sigma(x, u)|\mathbf{E}|^2, \quad (x, t) \in Q_T, \quad (1.3)$$

where

$$A(u) = \begin{cases} u - 1, & \text{if } u < m, \\ [m - 1, m], & \text{if } u = m, \\ u, & \text{if } u > m, \end{cases}$$

where the coefficient of heat conduction k may be different in solid and liquid phases:

$$k(x, u) = \begin{cases} k_l(x, u), & \text{if } u(x, t) < m, \\ k_s(x, u), & \text{if } u(x, t) > m, \end{cases}$$

Because of the heat source in Eq.(1.3), the interface set $\Gamma_T = \{(x, t) \in Q_T : u(x, t) = m\}$ may have positive area, i.e. mushy region may exist. In this case one has to define the value of heat conductivity $k(x, u)$ and $\sigma(x, u)$ on Γ_T and Eq.(1.2) is understood as an inclusion ([4]:

$$A(u)_t - \nabla[k(x, u)\nabla u] - \sigma(x, u)|\mathbf{E}|^2 \ni 0, \quad (x, t) \in Q_T.$$

Define

$$\begin{aligned} \sigma(x, m) & \text{ is between the values } \sigma_l(x, m+) \text{ and } \sigma_s(x, m-) \text{ for any } x \in \Gamma_T, \\ k(x, m) & \text{ is between the values of } k_l(x, m+) \text{ and } k_s(x, m-) \text{ for any } x \in \Gamma_T, \end{aligned}$$

where $\sigma_l(x, m+) = \lim_{u \rightarrow m+} \sigma_l(x, u)$ and other quantities are defined similarly.

If $\sigma(x, u)$ and $k(x, u)$ are independent of x . Then one can simply define

$$\sigma(m) \in [\sigma_0, \sigma_1], k(m) \in [k_0, k_1],$$

where constants k_0, k_1, σ_0 and σ_1 are defined as follows:

$$\begin{aligned} k_0 & = \min\{k_l(m), k_s(m)\}, k_1 = \max\{k_l(m), k_s(m)\}, \\ \sigma_0 & = \min\{\sigma_l(m), \sigma_s(m)\}, \sigma_1 = \max\{\sigma_l(m), \sigma_s(m)\}. \end{aligned}$$

To complete the problem, we prescribe the following initial and boundary conditions:

$$\mathbf{N} \times \mathbf{E}(x, t) = \mathbf{N} \times \mathbf{G}(x, t), \quad (x, t) \in S_T \tag{1.4}$$

$$u_n(x, t) = 0, \quad (x, t) \in S_T, \tag{1.5}$$

$$u(x, 0) = u_0(x), \quad x \in \Omega, \tag{1.6}$$

where $\mathbf{G}(x, t)$ is given external vector function on $S_T = \partial\Omega \times [0, T]$, \mathbf{N} is the outward normal on $S = \partial\Omega$, $u_n(x, t) := \nabla u \cdot \mathbf{N}$ is the normal derivative on S , $\mathbf{E}_0(x)$, $\mathbf{H}_0(x)$ and $u_0(x)$ are the prescribed initial electric, magnetic fields and initial temperature.

The Stefan-type free boundary problems have been studied extensively by many researchers (see Monographs [6, 11, 18] and many conference proceedings). The classical enthalpy method is widely used to describe a phase-change process (see [1, 3, 4, 5, 11, 15, 16] etc. for examples). For microwave heating problems without phase-change, some research has been carried out (see [7, 8, 12, 13, 19] etc. and also see recent lecture notes [22] Chapter 6 for the theory). When a phase-change takes place, Coleman in [2] studied the microwave melting in one-space dimension and obtained some numerical solutions. In [17], Pangrie et al. uses time-harmonic Maxwell's equations and the enthalpy method to model the microwave melting process and obtained the numerical solution for a radially symmetric domain by using finite-difference method. In [20] the author studied a phase-change problem arising from microwave heating processes in one-space dimension, where a kinetic type of condition is given on the interface due to the superheating phenomenon. Global existence and uniqueness are established in [20]. We would also like to mention a related work on a phase-change problem for the induction heating ([21]) recently, where displacement current is neglected and magnetic field is assumed to be time-harmonic. However, none of the previous research deals with the fully coupled system (1.1)-(1.3) with phase-change. One of the difficulties is that there is not much known about the regularity of solutions to Maxwell's equations with variable coefficients. Another difficulty is that the nonlinear term $\sigma(x, u)|\mathbf{E}|^2$ which only belongs to $L^1(Q_T)$. Moreover, the electric conductivity may have a jump discontinuity from solid to liquid phase. In this paper we study the phase-change problem (1.1)-(1.6). By using similar ideas from [21] it is shown that under certain conditions on coefficients of the system (1.1)-(1.3) the problem (1.1)-(1.6) has a global weak solution. The global existence is also established for the case when the electric and magnetic fields are assumed to be time-harmonic. Moreover, for one-space dimension we prove the existence of a weak solution for $\sigma(x, t, u)$ with linear growth in u -variable. In this paper the uniqueness is left out as an open question even for one-space dimension.

This paper is organized as follows. In section 2, we prove that the problem (1.1)-(1.6) has a weak solution in Q_T for any $T > 0$. In section 3, we study the problem for time-harmonic electric and magnetic fields and obtain the global solution for the problem. In section 4, we study the problem for one-space dimension and prove the existence of a weak solution for a more general function $\sigma(x, u)$.

2. Global Existence of Weak Solutions

In this section we first define weak solution to the problem and then consider an approximate problem by the standard approximation for $A(u)$ and $\sigma(u)$. It is shown that the approximated problem has a unique solution. Moreover, some uniform estimates for the approximate solution are derived. Finally, we establish the global existence to the problem (1.1)-(1.5) by using a compactness argument.

We list some basic assumptions for the coefficients and the known data.

H(2.1): (a) Let $\varepsilon(x)$ and $\mu(x)$ be in $L^\infty(\Omega)$ with a positive lower bound

$$0 < r_0 \leq \varepsilon(x), \mu(x) \leq R_0, \quad x \in \Omega,$$

where r_0 and R_0 are positive constants.

(b) $\sigma(x, u)$ is non-negative and is bounded in $\Omega \times [M, \infty)$ for some large $M > 0$ and σ_0 :

$$0 \leq \sigma(x, u) \leq \sigma_0, u\sigma(x, u) \leq \sigma_0, \quad (x, u) \in \Omega \times [M, \infty).$$

(c) The functions $k_l(x, u)$ and $k_s(x, u)$ are of class $C^{1+\alpha}(\Omega \times R)$ and bounded with a positive lower bound:

$$0 < r_0 \leq k_s(x, u), k_l(x, u) \leq R_0, \quad (x, u) \in \Omega \times [0, \infty).$$

H(2.2): (a) Let $u_0(x)$ be in $L^\infty(\Omega)$ and $\mathbf{E}_0(x), \mathbf{H}_0(x) \in L^2(\Omega)^3$.

(b) Let $\mathbf{G}(x, t) \in C([0, T]; H^{\frac{1}{2}}(S))$.

It is easy to see that the conditions on $\sigma(x, u)$ are satisfied for $\sigma(x, u) = \frac{1}{(1+u)^p}$ with $p \geq 1$ or $\sigma(x, u) = a(x)e^{-u}$. For reader's convenience, we recall some function spaces associated with Maxwell's equations. Other Sobolev spaces are the same as in [10].

Let

$$\begin{aligned} H(\mathit{curl}, \Omega) &= \{\mathbf{V} \in L^2(\Omega)^3 : \nabla \times \mathbf{V} \in L^2(\Omega)^3\}; \\ H_0(\mathit{curl}, \Omega) &= \{\mathbf{V} \in H(\mathit{curl}, \Omega) : \mathbf{N} \times \mathbf{V} = 0 \text{ on } \partial\Omega\}. \end{aligned}$$

$H(\mathit{curl}, \Omega)$ is a Hilbert space equipped with inner product

$$(\mathbf{V}, \mathbf{K}) = \int_{\Omega} [\mathbf{V} \cdot \mathbf{K} + (\nabla \times \mathbf{V}) \cdot (\nabla \times \mathbf{K})] dx.$$

Definition 2.1: A triple of functions $(\mathbf{E}(x, t), \mathbf{H}(x, t), u(x, t))$ is said to be a weak solution to the problem (1.1)-(1.6), if

$$\mathbf{E}(x, t), \mathbf{H}(x, t) \in C([0, T]; L^2(\Omega)),$$

and $u(x, t) \in L^2(0, T; H^1(\Omega)) \cap C([0, T]; L^2(\Omega))$, which satisfy the following integral identities:

$$\begin{aligned} \int_0^T \int_{\Omega} [-\varepsilon \mathbf{E} \cdot \boldsymbol{\Psi}_t + \sigma \mathbf{E} \cdot \boldsymbol{\Psi}] dx dt &= \int_0^T \int_{\Omega} [\mathbf{H} \cdot (\nabla \times \boldsymbol{\Psi})] dx dt + \int_{\Omega} \varepsilon \mathbf{E}_0 \cdot \boldsymbol{\Psi}(x, 0) dx, \\ \int_0^T \int_{\Omega} [-\mu \mathbf{H} \cdot \boldsymbol{\Phi}_t + \mathbf{E} \cdot (\nabla \times \boldsymbol{\Phi})] dx dt &= \int_{\Omega} [\mu \mathbf{H}_0(x) \cdot \boldsymbol{\Phi}(x, 0)] dx, \\ \int_0^T \int_{\Omega} [-A(u) \psi_t + k(x, u) \nabla u \nabla \psi] dx dt &= \int_0^T \int_{\Omega} \sigma(x, u) |\mathbf{E}|^2 \psi dx dt + \int_{\Omega} A(u_0) \psi dx \end{aligned}$$

for any test vector functions $\boldsymbol{\Psi}, \boldsymbol{\Phi} \in L^2(0, T; H_0(\text{curl}, \Omega)) \cap C([0, T]; L^2(\Omega)^3)$ and any test function $\psi \in H^1(0, T; H^1(\Omega))$ with $\boldsymbol{\Psi}(x, T) = \boldsymbol{\Phi}(x, T) = 0$ and $\psi(x, T) = 0$ on Ω .

Since the weak solution $\mathbf{E}(x, t) \in L^2(\Omega)$, we have to specify the boundary condition (1.4) in the weak sense. Note that

$$\mathbf{H}(x, t) = \mathbf{H}_0(x) - \frac{1}{\mu(x)} \int_0^t \nabla \times \mathbf{E}(x, \tau) d\tau = \mathbf{H}_0(x) - \frac{1}{\mu(x)} \nabla \times \mathbf{W}(x, t),$$

where

$$\mathbf{W}(x, t) = \int_0^t \mathbf{E}(x, \tau) d\tau.$$

It follows that $\mathbf{H} \in L^2(\Omega)^3$ implied $\nabla \times \mathbf{W} \in L^2(\Omega)^3$ for each a.e. fixed $t \in [0, T]$. Consequently, the trace $\mathbf{N} \times \mathbf{W}(x, t)$ is well-defined on $\partial\Omega$. We define

$$\mathbf{N} \times (\mathbf{E}(x, t) - \mathbf{G}(x, t)) = 0, \quad (x, t) \in S_T$$

if and only if

$$\mathbf{N} \times [\mathbf{W}(x, t) - \int_0^t \mathbf{G}(x, \tau) d\tau] = 0, \quad (x, t) \in S_T.$$

Introduce a new function,

$$U(x, t) := K(x, u) = \int_m^u k(x, s) ds, \quad (x, t) \in Q_T.$$

Then the assumption H(2.1)(b) implies that the inverse function $u(x, t) = K^{-1}(x, U)$ exists. Consequently, Eq. (1.3) can be written in the weak sense as follows:

$$A^*(x, U)_t - \Delta U = \sigma^*(x, U)|\mathbf{E}|^2, \quad (x, t) \in Q_T,$$

where

$$A^*(x, U) = \begin{cases} K_s^{-1}(x, U) - 1, & \text{if } U < 0, \\ [-1, 0], & \text{if } U = 0, \\ K_l^{-1}(x, U), & \text{if } U > 0, \end{cases}$$

and $K_s^{-1}(x, U), K_l^{-1}(x, U)$ are the inverse functions of $K_s(x, u), K_l(x, u)$, respectively. Moreover,

$$\sigma^*(x, U) = \begin{cases} \sigma(x, K_s^{-1}(x, U)), & \text{if } U < 0, \\ [\sigma_0, \sigma_1], & \text{if } U = 0, \\ \sigma(x, K_l^{-1}(x, U)), & \text{if } U > 0. \end{cases}$$

From now on, instead of using $U(x, t), A^*(x, U)$ and $\sigma^*(x, U)$ we will continue to use notation $u(x, t), A(x, u)$ and $\sigma(x, u)$ for simplicity. By assumption H(2.2), there exists an extension for $\mathbf{G}(x, t)$ such that $\mathbf{G}(x, t) \in C([0, T]; H^1(\Omega)^3)$. Moreover, from the assumption of H(2.1)(c) there exists a constant $a_0 > 0$ such that $A'(x, u) := A_u(x, u) \geq a_0$ for all $(x, u) \in \Omega \times R$ whenever $u \neq m$.

Let $A_n(x, u)$ and $\sigma_n(x, u)$ be the smooth approximation of $A(x, u)$ and $\sigma(x, u)$, respectively. Moreover, we require that

$$\begin{aligned} A_n(x, u) &= A(x, u), \sigma_n(x, u) = \sigma(x, u), \text{ if } |u - m| \geq \frac{1}{n}, \\ A'_n(x, u) &\geq \frac{r_0}{2}, A_n(x, u) \rightarrow A(x, u), \sigma_n(x, u) \rightarrow \sigma(x, u) \end{aligned}$$

strongly in $L^2(\Omega \times [-M, M])$ for some large $M > 0$ as $n \rightarrow \infty$. We also make a smooth approximation for $u_0(x)$, denoted by $u_{0n}(x)$, such that $\nabla u_{0n}(x) = 0$ on S and $u_{0n}(x) \rightarrow u_0(x)$ strongly in $L^2(Q_T)$.

Consider the following approximate system:

$$\varepsilon(x)\mathbf{E}_t + \sigma_n(x, u)\mathbf{E} = \nabla \times \mathbf{H}, \quad (x, t) \in Q_T, \quad (2.1)$$

$$\mu(x)\mathbf{H}_t + \nabla \times \mathbf{H} = 0, \quad (x, t) \in Q_T, \quad (2.2)$$

$$A_n(x, u)_t - \Delta u = \sigma_n(x, u)|\mathbf{E}|^2, \quad (x, t) \in Q_T, \quad (2.3)$$

$$\mathbf{N} \times \mathbf{E}(x, t) = \mathbf{N} \times \mathbf{G}(x, t), \quad (x, t) \in S_T, \quad (2.4)$$

$$u_n(x, t) = 0, \quad (x, t) \in S_T, \quad (2.5)$$

$$\mathbf{E}(x, 0) = \mathbf{E}_0(x), \mathbf{H}(x, 0) = \mathbf{H}_0(x), u(x, 0) = u_{0n}(x), x \in \Omega. \quad (2.6)$$

From Theorem 2.1 ([19]), the problem (2.1)-(2.6) has a unique weak solution

$$(\mathbf{E}_n(x, t), \mathbf{H}_n(x, t)) \in C([0, T]; H_0(\text{curl}, \Omega)) \times C([0, T]; H(\text{curl}, \Omega))$$

and

$$u_n(x, t) \in C([0, T]; L^2(\Omega)) \cap L^2(0, T; H^1(\Omega)).$$

Moreover,

$$\mathbf{E}_n(x, t) - \mathbf{G}(x, t) \in L^\infty(0, T; H_0(\text{curl}, \Omega)).$$

Furthermore, since $u_0(x) \in L^\infty(\Omega)$ and $\sigma_n(x, u)|\mathbf{E}|^2 \geq 0$, it follows from the maximum principle that there exists a constant $M_0 > 0$ independent of n such that $u_n(x, t) \geq -M_0$ on Q_T .

Now we derive some uniform estimates.

Lemma 2.1: There exist constant C_1 such that

$$\sup_{0 \leq t \leq T} \int_{\Omega} [|\mathbf{E}_n|^2 + |\mathbf{H}_n|^2] dx \leq C_1,$$

where C_1 depends only on the known data.

Proof: For simplicity, we shall drop the subscript n for the solution $(\mathbf{E}_n, \mathbf{H}_n, u_n)$ whenever without causing confusion. To derive the estimate, we take the inner product by $\mathbf{E}(x, t) - \mathbf{G}$ to Eq. (2.1) and by $\mathbf{H}(x, t)$ to Eq. (2.2), respectively, to obtain:

$$\begin{aligned} & \frac{d}{dt} \frac{1}{2} \int_{\Omega} [\varepsilon |\mathbf{E}|^2] dx + \int_{\Omega} \sigma(x, u) |\mathbf{E}|^2 dx \\ &= \int_{\Omega} \varepsilon \mathbf{E} \cdot \mathbf{G} dx + \int_{\Omega} [\sigma \mathbf{E} \cdot \mathbf{G}] dx + \int_{\Omega} [\nabla \times \mathbf{H} \cdot (\mathbf{E} - \mathbf{G})] dx, \\ & \frac{d}{dt} \frac{1}{2} \int_{\Omega} [\mu |\mathbf{H}|^2] dx + \int_{\Omega} [\nabla \times \mathbf{E} \cdot \mathbf{H}] dx = 0. \end{aligned}$$

We add up the above equations and use the fact,

$$\int_{\Omega} \nabla \times \mathbf{H} \cdot (\mathbf{E} - \mathbf{G}) dx = \int_{\Omega} \mathbf{H} \cdot [\nabla \times (\mathbf{E} - \mathbf{G})] dx,$$

to obtain

$$\begin{aligned} & \frac{d}{dt} \frac{1}{2} \int_{\Omega} [\varepsilon |\mathbf{E}|^2 + \mu |\mathbf{H}|^2] dx + \int_{\Omega} \sigma(x, u) |\mathbf{E}|^2 dx \\ & \leq C \int_{\Omega} [|\mathbf{E}|^2 + |\mathbf{H}|^2] dx + C \int_{\Omega} [|\mathbf{G}|^2 + |\nabla \times \mathbf{G}|^2] dx, \end{aligned}$$

where C depends only on L^∞ -bounds of $\varepsilon(x)$, $\mu(x)$ and $\sigma(x, u)$, but independent of n . Gronwall's inequality yields the desired estimate.

Q.E.D.

Lemma 2.2: There exists a constant C_2 such that

$$\sup_{0 \leq t \leq T} \int_{\Omega} |u_n|^2 dx + \int \int_{Q_T} |\nabla u_n|^2 dx dt \leq C_2,$$

where C_2 depends only on known data.

Proof: Since $A'_n(x, u) \geq \frac{r_0}{2}$, the inverse of the function for $v(x, t) := A_n(x, u)$ exists, denoted by $u = B_n(x, v)$. Then

$$\begin{aligned} & \int_0^t \int_{\Omega} A_n(u)_t u dx dt = \int_0^t \left[\frac{d}{dt} \int_{\Omega} \int_0^v B_n(x, s) ds dx \right] dt \\ & = \int_{\Omega} \int_0^v B_n(x, s) ds dx - \int_{\Omega} \int_0^{A_n(u_0)} B_n(x, s) ds dx \\ & \geq b_0 \int_{\Omega} u^2 dx - C, \end{aligned}$$

for some $b_0 > 0$ since $k_0 s \leq B_n(x, s) \leq k_1(s + 1)$ from the assumption H(2.1)(c).

On the other hand, it is clear that

$$- \int_0^t \int_{\Omega} (\Delta u) u dx dt = \int_0^t \int_{\Omega} |\nabla u|^2 dx dt.$$

Moreover, by Lemma 2.1 and the assumption H(2.1) we have

$$\int_{\Omega} \sigma(x, u) u |\mathbf{E}|^2 dx \leq C,$$

where C depends only on known data.

We sum up the above estimates to obtain

$$\int_{\Omega} u^2 dx + \int_0^t \int_{\Omega} |\nabla u|^2 dx dt \leq C_2,$$

where C_2 depends only on known data.

Q. E. D.

To prove the existence of a weak solution for the problem (1.1)-(1.6), we need the following lemma from [19].

Lemma 2.3: Suppose $\sigma_n(x, t) \rightarrow \sigma(x, t)$ strongly in $L^2(Q_T)$. Let $(\mathbf{E}_n(x, t), \mathbf{H}_n(x, t))$ be the solution of the Maxwell equations:

$$\begin{aligned} \varepsilon \mathbf{E}_t + \sigma_n(x, t) \mathbf{E} &= \nabla \times \mathbf{H}, & (x, t) \in Q_T, \\ \mu \mathbf{H}_t + \nabla \times \mathbf{E} &= 0, & (x, t) \in Q_T, \\ \mathbf{N} \times \mathbf{E} &= \mathbf{N} \times \mathbf{G}, & (x, t) \in \partial\Omega \times (0, T], \\ \mathbf{E}(x, 0) &= \mathbf{E}_0(x), \mathbf{H}(x, 0) = \mathbf{H}_0(x), & x \in \Omega. \end{aligned}$$

Let $(\mathbf{E}(x, t), \mathbf{H}(x, t))$ be the solution of the above Maxwell equations where $\sigma_n(x, t)$ is replaced by $\sigma(x, t)$. Then $(\mathbf{E}_n(x, t), \mathbf{H}_n(x, t))$ converges to $(\mathbf{E}(x, t), \mathbf{H}(x, t))$ strongly in $L^2(Q_T)$.

Q.E.D.

Theorem 2.4: The problem (1.1)-(1.6) possesses at least one weak solution in Q_T for any $T > 0$.

Proof: From Lemma 2.1-2.2 and the weak compactness, we know, after extracting a subsequence if necessary, that

$$\begin{aligned} \mathbf{E}_n(x, t) &\rightarrow \mathbf{E}(x, t), \mathbf{H}_n(x, t) \rightarrow \mathbf{H}(x, t) \text{ in weak-}^* L^\infty(0, T; L^2(\Omega)^3), \\ u_n(x, t) &\rightarrow u(x, t) \text{ weakly in } L^2(0, T; H^1(\Omega)). \end{aligned}$$

Moreover, by applying the result of Lemma 5.1 from [15] we see that $u_n(x, t)$ converges to $u(x, t)$ strongly in $L^2(Q_T)$ and almost everywhere in Q_T .

We multiply Eq.(2.1) and Eq.(2.2) by any test vector functions $\Psi(x, t)$ and $\Phi(x, t)$, respectively, in $H^1(0, T; H_0(\text{curl}, \Omega))$ to obtain

$$\begin{aligned} &\int_0^T \int_\Omega [-\varepsilon \mathbf{E}_n \cdot \Psi_t + \sigma_n(x, u_n) \mathbf{E}_n \cdot \Psi] dx dt \\ &= \int_0^T \int_\Omega [\mathbf{H}_n \cdot (\nabla \times \Psi)] dx dt + \int_\Omega \varepsilon \mathbf{E}_0(x) \cdot \Psi(x, 0) dx, \\ &\int_\Omega [-\mu \mathbf{H}_n \cdot \Phi_t + \mathbf{E}_n \cdot (\nabla \times \Phi)] dx dt = \int_\Omega [\mu \mathbf{H}_0(x) \cdot \Phi(x, 0)] dx. \end{aligned}$$

After taking limit as $n \rightarrow \infty$, we see that (\mathbf{E}, \mathbf{H}) satisfies the integral identities in Definition 2.1 if we can prove $\mathbf{J}_n(x, t) := \sigma_n(x, u_n)\mathbf{E}_n$ converges to $\mathbf{J}(x, t) = \sigma(x, u)\mathbf{E}(x, t)$ weakly in $L^2(Q_T)$. We skip the proof here since it can be done by using the same technique as for a more complicated term $\sigma_n(x, u_n)|\mathbf{E}_n|^2$ below (see detailed proof below). Moreover, since $\mathbf{E}_n(x, t) - \mathbf{G}(x, t) \in L^\infty(0, T; H_0(\text{curl}, \Omega))$ and $\mathbf{H}_n(x, t) \in L^\infty([0, T]; L^2(\Omega))$, it follows that $\nabla \times \mathbf{W}_n(x, t) \in L^\infty([0, T], L^2(\Omega))$, where

$$\mathbf{W}_n(x, t) = \int_0^t \mathbf{E}_n(x, \tau) d\tau.$$

Thus, the trace $\mathbf{N} \times \mathbf{W}_n$ is well defined on $\partial\Omega$. Since $\mathbf{N} \times \mathbf{W}_n = \mathbf{N} \times \int_0^t \mathbf{G}(x, \tau) d\tau$ and $\mathbf{N} \times [\mathbf{E}_n - \mathbf{G}] = 0$ is equivalent to $\mathbf{N} \times [\mathbf{W}_n - \int_0^t \mathbf{G}(x, \tau) d\tau] = 0$. It follows that the boundary condition (1.4) holds.

For any small $\gamma > 0$ by Egorof's theorem there exists a subset $Q \subset Q_T$ with $|Q_T \setminus Q| < \gamma$ such that $u_n(x, t)$ converges to $u(x, t)$ uniformly on Q . Set $Q_\gamma = \{(x, t) \in Q : |u(x, t) - m| > \gamma\}$. Then, for $(x, t) \in Q_\gamma$, if n is sufficiently large,

$$|u_n(x, t) - m| \geq \frac{\gamma}{2} \geq \frac{1}{n}.$$

On the other hand, for any $(x, t) \in Q \setminus Q_\gamma$

$$|u_n - u| \leq |u_n - m| + |u - m| \leq 2\gamma,$$

provided that n is large enough.

Let ϕ be a smooth test vector function.

$$\begin{aligned} & \int \int_{Q_T} [\sigma_n(x, u_n)|\mathbf{E}_n|^2 - \sigma(x, u)|\mathbf{E}|^2] \phi dx dt \\ &= \int \int_Q [\sigma_n(x, u_n)|\mathbf{E}_n|^2 - \sigma(x, u)|\mathbf{E}|^2] \phi dx dt + \\ & \int \int_{Q_T \setminus Q} [\sigma_n(x, u_n)|\mathbf{E}_n|^2 - \sigma(x, u)|\mathbf{E}|^2] \phi dx dt \\ &:= I_1 + I_2. \end{aligned}$$

It is clear that $I_2 \rightarrow 0$ as $\gamma \rightarrow 0$ since $|Q_T \setminus Q| < \gamma$.

$$\begin{aligned} I_1 &:= \int \int_{Q_\gamma} [\sigma(x, u_n)|\mathbf{E}_n|^2 - \sigma(x, u)|\mathbf{E}|^2] \phi dx dt \\ &+ \int \int_{Q \setminus Q_\gamma} [\sigma_n(x, u_n)|\mathbf{E}_n|^2 - \sigma(x, u)|\mathbf{E}|^2] \phi dx dt := J_1 + J_2. \end{aligned}$$

$$\begin{aligned}
|J_1| &\leq \left| \int \int_{Q_\gamma} \sigma(x, u_n) [|\mathbf{E}_n|^2 - |\mathbf{E}|^2] |\phi| dxdt \right| + \int \int_{Q_\gamma} |\sigma(x, u_n) - \sigma(x, u)| |\mathbf{E}|^2 |\phi| dxdt \\
&:= J_{11} + J_{12}.
\end{aligned}$$

It is clear that $J_{11} \rightarrow 0$ since \mathbf{E}_n converges to \mathbf{E} strongly in $L^2(Q_T)$ by Lemma 2.3 and $\sigma(x, u_n)$ is bounded. On the other hand,

$$Q_\gamma = [Q_\gamma \cap \{(x, t) \in Q : u(x, t) \geq m + \gamma\}] \cup [Q_\gamma \cap \{(x, t) \in Q : u(x, t) \leq m - \gamma\}].$$

Since $u_n \rightarrow u(x, t)$ a.e. on Q_T and uniformly in Q , it follows that on $Q_\gamma \cap \{(x, t) : u(x, t) \geq m + \gamma\}$, $\sigma(x, u_n) = \sigma_l(x, u_n) \rightarrow \sigma_l(x, u)$ a.e. and on $Q_\gamma \cap \{(x, t) : u(x, t) \leq m - \gamma\}$, $\sigma(x, u_n) = \sigma_s(x, u_n) \rightarrow \sigma_s(x, u)$ a.e. as $n \rightarrow \infty$, by dominated convergence theorem we see $J_{12} \rightarrow 0$ as $n \rightarrow \infty$.

Next we prove $J_2 \rightarrow 0$ as $n \rightarrow \infty$. Without loss of generality, we assume

$$\sigma_s(x, m) \leq \sigma_l(x, m), \quad x \in \Omega.$$

Then the approximation sequence $\sigma_n(x, u)$ can be assumed to be increasing in u -variable in a neighborhood of $u = m$. On $Q \setminus Q_\gamma$,

$$m - \gamma \leq u_n(x, t) \leq m + \gamma,$$

As $\sigma_n(x, u)$ is increasing in a neighborhood of $u = m$, we see

$$\sigma_n(x, m - \gamma) \leq \sigma_n(x, u_n) \leq \sigma_n(x, m + \gamma).$$

If n is sufficiently large,

$$\sigma_n(x, m - \gamma) = \sigma_s(x, m - \gamma), \sigma_n(x, m + \gamma) = \sigma_l(x, m + \gamma).$$

By the weak convergence and the definition of $\sigma(x, m)$, when $\gamma \rightarrow 0, n \rightarrow \infty$ we have

$$\sigma_s(x, m-) \leq \sigma(x, m) \leq \sigma(x, m+), \quad a.e. x \in \Omega.$$

It follows that

$$\begin{aligned}
|J_2| &\leq \left| \int \int_{Q \setminus Q_\gamma} [\sigma_n(x, u_n) (|\mathbf{E}_n|^2 - |\mathbf{E}|^2)] |\phi| dxdt \right| \\
&\quad + \left| \int \int_{Q \setminus Q_\gamma} (\sigma_n(x, u_n) - \sigma(x, u)) |\mathbf{E}|^2 |\phi| dxdt \right| \rightarrow 0
\end{aligned}$$

as $n \rightarrow \infty, \gamma \rightarrow 0$.

Next we consider the convergence for $A_n(x, u_n)$. The weak compactness implies that there exists a function $\beta(x, t) \in L^2(Q_T)$ such that $A_n(u_n) \rightarrow \beta(x, t)$ weakly in $L^2(Q_T)$. We need to prove that the graph of $\beta(x, t) \in A(u)$ a.e. on Q_T . From the construction of A_n and convergence of u_n we see

$$\beta(x, t) = A(u) \text{ a.e. on } Q_\gamma.$$

On $Q_T \setminus Q_\gamma$,

$$m - \frac{2}{n} \leq u_n \leq m + \frac{2}{n}.$$

The monotonicity of $A(u)$ implies

$$A_n(m - \frac{2}{n}) \leq A_n(u_n) \leq A_n(m + \frac{2}{n}),$$

which is the same as

$$A(m - \frac{2}{n}) \leq A_n(u_n) \leq A(m + \frac{2}{n}).$$

The weak convergence yields that for a.e. $(x, t) \in Q_T \setminus Q_\gamma$

$$m - 1 \leq \beta(x, t) \leq m.$$

Now we multiply Eq. (2.3) by any test function $\psi \in H^1(0, T; H^1(\Omega))$ with $\psi(x, T) = 0$ and then integrate over Q_T to obtain

$$\begin{aligned} & \int_0^T \int_\Omega [-A_n(x, u_n)\psi_t + \nabla u_n \nabla \psi] dx \\ &= \int_0^T \int_\Omega \sigma(x, u_n) |\mathbf{E}_n|^2 \psi dx dt + \int_\Omega A(x, u_{0n}(x)) \psi(x, 0) dx. \end{aligned}$$

Finally, we take limit as $n \rightarrow \infty$ to see that $(\mathbf{E}(x, t), \mathbf{H}(x, t), u(x, t))$ is indeed a weak solution of the problem (1.1)-(1.6). Q.E.D.

3. Global Existence in Time-Harmonic Fields

For some industrial applications (see [12, 13]), the time scale for electromagnetic field and the heat conduction is quite different. It is often to assume that the electric and magnetic fields are time-harmonic. This leads to the following problem:

$$i\mu\omega\mathbf{H} + \nabla \times \mathbf{E} = 0, \quad x \in \Omega, \quad (3.1)$$

$$(i\varepsilon\omega + \sigma)\mathbf{E} = \nabla \times \mathbf{H}, \quad x \in \Omega, \quad (3.2)$$

where i represents the complex unit and ω is the frequency.

For many applied problems, it is often convenient to use a unified approach by assuming that (see [12]):

$$\varepsilon(x) = \varepsilon_1(x) + i\varepsilon_2(x), \mu(x) = \mu_1(x) - i\mu_2(x),$$

where $\varepsilon_1(x), \varepsilon_2(x), \mu_1(x)$ and $\mu_2(x)$ are positive functions.

It is clear that the system (3.1)-(3.2) is equivalent to the following one:

$$\nabla \times [\gamma(x)\nabla \times \mathbf{E}] + r(x, u)\mathbf{E} = 0, \quad x \in \Omega, \quad (3.3)$$

where

$$\begin{aligned} \gamma(x) &:= \frac{1}{\mu(x)} = \frac{\mu_1}{\sqrt{|\mu_1|^2 + |\mu_2|^2}} + i\frac{\mu_2}{\sqrt{|\mu_1|^2 + |\mu_2|^2}}, \\ r(x, u) &:= i\omega(i\varepsilon(x)\omega + \sigma(x, u)). \end{aligned}$$

Consider the phase-change problem:

$$\nabla \times [\gamma(x)\nabla \times \mathbf{E}] + r(x, u)\mathbf{E} = 0, \quad x \in \Omega, \quad (3.4)$$

$$A(x, u)_t - \Delta u = \sigma(x, u)|\mathbf{E}|^2, \quad (x, t) \in Q_T, \quad (3.5)$$

$$\mathbf{N} \times \mathbf{E}(x) = \mathbf{N} \times \mathbf{G}(x), \quad x \in \partial\Omega, \quad (3.6)$$

$$u_n(x, t) = 0, \quad (x, t) \in \partial\Omega \times (0, T], \quad (3.7)$$

$$u(x, 0) = u_0(x), \quad x \in \Omega. \quad (3.8)$$

Note that the coefficient $\sigma(x, u)$ depends on t since $u(x, t)$ is a function of t . The solution \mathbf{E} is also a function of t . However, this time variable for the heat conduction is different from the time-variable in electromagnetic field.

A weak solution to (3.4)-(3.8) can be defined as follows.

Definition 3.1: A pair functions $(\mathbf{E}(x, t), u(x, t))$ is called a weak solution of (3.4)-(3.8) if $\mathbf{E}(x, t) \in H(\text{curl}, \Omega)$, $u(x, t) \in L^2(0, T; H^1(\Omega))$ with $\mathbf{N} \times (\mathbf{E} - \mathbf{G}) \in H_0(\text{curl}, \Omega)$ and the following integral identities hold:

$$\begin{aligned} \int_{\Omega} [\gamma(\nabla \times \mathbf{E}) \cdot (\nabla \times \boldsymbol{\Psi}) + r(x, u)\mathbf{E} \cdot \boldsymbol{\Psi}] dx &= 0, \\ \int \int_{Q_T} [-A(x, u)\psi_t + \nabla u \nabla \psi] dx dt &= \int \int_{\Omega_T} \sigma(x, u)|\mathbf{E}|^2 \psi dx dt + \int_{\Omega} A(x, u_0)\psi(x, 0) dx \end{aligned}$$

for any test vector functions $\mathbf{\Psi} \in H_0(\text{curl}, \Omega)$ and any test function $\psi \in H^1(0, T; H^1(\Omega))$ with $\psi(x, T) = 0$ on Ω .

H(3.1): (a) Let $\varepsilon_1(x), \varepsilon_2(x), \mu_1(x)$ and $\mu_2(x)$ be nonnegative and of class $L^\infty(\Omega)$ with $\varepsilon_1 \geq r_0, \varepsilon_2 \geq 0$. Let

$$0 \leq \sigma(x, u) \leq \sigma_0, u\sigma(x, u) \leq \sigma_1, u \in [M, \infty).$$

Moreover, there exists a constant σ_1 such that

$$\sigma(x, u) - |\varepsilon_2|_{L^\infty(\Omega)} \geq \sigma_1 > 0.$$

(b) Let $\mathbf{G}(x) \in H(\text{curl}, \Omega)$.

H(3.2): Let $A(x, u)$ be defined as in section 2 and satisfy the same condition as in H(2.1)(c). Moreover, $u_0(x) \in L^2(\Omega)$ and nonnegative.

Theorem 3.1 Under the assumptions H(3.1)-(3.3) the problem (3.4)-(3.8) has a global weak solution.

Proof: As the proof is quite similar to that of Theorem 2.4, we only give an outline.
Step 1: Approximating the problem. By constructing smooth approximation for σ and $A(x, u)$, we consider the approximation problem:

$$\nabla \times [\gamma(x)\nabla \times \mathbf{E}] + r_n(x, u)\mathbf{E} = 0, \quad x \in \Omega, \quad (3.9)$$

$$A_n(x, u)_t - \Delta u = \sigma_n(x, u)|\mathbf{E}|^2, \quad (x, t) \in Q_T, \quad (3.10)$$

$$\mathbf{N} \times \mathbf{E} = \mathbf{N} \times \mathbf{G}, \quad x \in \partial\Omega, \quad (3.11)$$

$$u_n(x, t) = 0, \quad (x, t) \in \partial\Omega \times (0, T], \quad (3.12)$$

$$u(x, 0) = u_0(x), \quad x \in \Omega. \quad (3.13)$$

This problem has at least one weak solution $(\mathbf{E}_n(x, t), u_n(x, t))$ ([21]).

Step 2: Deriving uniform estimates.

There exist constants C_1 and C_2 independent of n such that

$$\begin{aligned} \int_{\Omega} |\nabla \times \mathbf{E}_n|^2 dx + \int_{\Omega} |\mathbf{E}_n|^2 dx &\leq C_1, \\ \sup_{0 \leq t \leq T} \int_{\Omega} u_n^2 dx + \int \int_{Q_T} |\nabla u_n|^2 dx dt &\leq C_2. \end{aligned}$$

To prove the first estimate, we take the inner product by $(\mathbf{E} - \mathbf{G})^*$, the complex conjugate of $\mathbf{E} - \mathbf{G}$, to Eq.(3.9) to obtain

$$\int_{\Omega} \gamma(\nabla \times \mathbf{E}) \cdot [\nabla \times (\mathbf{E} - \mathbf{G})^*] + r_n(x, u)\mathbf{E} \cdot (\mathbf{E} - \mathbf{G})^* dx = 0. \quad (3.14)$$

We first take the imaginary part of the above equation to obtain

$$\int_{\Omega} \frac{\mu_2}{\sqrt{\mu_1^2 + \mu_2^2}} |\nabla \times \mathbf{E}|^2 dx + \int_{\Omega} (\sigma - \varepsilon_2) |\mathbf{E}|^2 dx \leq C,$$

where the constant C depends only on known data. By H(3.1), we obtain

$$\int_{\Omega} |\mathbf{E}|^2 dx \leq \frac{C}{\sigma_1}.$$

Now we take the real part of Eq. (3.15) and use the assumption H(3.1) again to obtain

$$\int_{\Omega} |\nabla \times \mathbf{E}|^2 dx \leq C,$$

where C depends only on known data.

The second estimate is the same as Lemma 2.3.

Step 3: Taking the limit. This step is almost identical to that of Theorem 2.4, we skip it here.

Q.E.D.

Remark 3.1: The assumption H(3.1) is only one type of sufficient conditions to ensure the global existence of a unique weak solution to time-harmonic Maxwell's equations. Other types of sufficient conditions can be found in [14, 22].

4. One-dimensional Problem

In this section we study the problem (1.1)-(1.5) in one space dimension and prove that the weak solution exists globally for $\sigma(x, t, u)$ with linear growth.

Let $Q_T = \{(x, t) : 0 < x < 1, 0 < t < T\}$. For one-space dimension, we assume $\mathbf{E}(x, t) = \{0, e(x, t), 0\}$, $\mathbf{H}(x, t) = \{0, 0, h(x, t)\}$. Then the system (1.1)-(1.3) becomes the following form:

$$\varepsilon(x)e_t + \sigma(x, t, u)e = -h_x, \quad (x, t) \in Q_T, \quad (4.1)$$

$$\mu(x)h_t + e_x = 0, \quad (x, t) \in Q_T, \quad (4.2)$$

$$A(x, u)_t - u_{xx} = \sigma(x, t, u)|e(x, t)|^2, \quad (x, t) \in Q_T, \quad (4.3)$$

where $A(x, u)$ is the same as in Section 2.

By solving $h(x, t)$ from Eq.(4.2), we see

$$h(x, t) = h_0(x) - \frac{1}{\mu(x)} w_x(x, t), \quad (x, t) \in Q_T,$$

where

$$w(x, t) = \int_0^t e(x, \tau) d\tau.$$

For simplicity, we assume $h_0(x) = 0$ on Q_T . It follows that Eq.(4.1)-(4.3) is equivalent to the following system:

$$\varepsilon(x)w_{tt} - (\gamma(x)w_x)_x + \sigma(x, t, u)w_t = 0, \quad (4.4)$$

$$A(x, u)_t - u_{xx} = \sigma(x, t, u)|w_t(x, t)|^2, \quad (x, t) \in Q_T. \quad (4.5)$$

The initial and boundary conditions are as follows:

$$w(0, t) = f_1(t), w(1, t) = f_2(t), u_x(0, t) = u_x(1, t) = 0, t \in [0, T], \quad (4.6)$$

$$w(x, 0) = 0, w_t(x, 0) = e_0(x), u(x, 0) = u_0(x), \quad 0 < x < 1. \quad (4.7)$$

H(4.1): (a) Let $\varepsilon(x), \gamma(x)$ satisfies H(2.1)(a). Let $\sigma(x, t, u)$ satisfies

$$0 \leq \sigma(x, t, u) \leq \sigma_0(1 + u), (x, t, u) \in Q_T \times [0, \infty).$$

(b) Let $A(x, u)$ be defined as in section 2 and satisfy the same condition as in H(2.1)(c).

(c) Let $f_1(t), f_2(t) \in H^1(0, T)$ with $f_1(0) = f_2(0) = 0$ and $e_0(x), u_0(x) \in L^2(0, 1)$.

Theorem 4.1: Under the assumption H(4.1) the problem (4.4)-(4.7) has a weak solution globally.

Proof: As for n -dimensional case, we make a smooth approximation for $\sigma(x, t, u)$ and $A(x, u)$ and then consider the following approximate problem:

$$\varepsilon(x)w_{tt} - (\gamma(x)w_x)_x + \sigma_n(x, t, u)w_t = 0, \quad (x, t) \in Q_T, \quad (4.8)$$

$$A_n(x, u)_t - u_{xx} = \sigma_n(x, t, u)|w_t(x, t)|^2, \quad (x, t) \in Q_T, \quad (4.9)$$

$$w(0, t) = f_1(t), w(1, t) = f_2(t), u_x(0, t) = u_x(1, t) = 0, t \in [0, T], \quad (4.10)$$

$$w(x, 0) = 0, w_t(x, 0) = e_0(x), u(x, 0) = u_0(x), \quad 0 < x < 1. \quad (4.11)$$

This problem has a unique weak solution ([19])

$$(w_n(x, t), u_n(x, t)) \in H^1(0, T; H^1(0, 1)) \times L^2(0, T; H^1(0, 1)).$$

Again we will omit the subscript n . Now we derive some uniform estimates. First of all, set

$$g(x, t) = (1 - x)f_1(t) + xf_2(t), (x, t) \in Q_T.$$

We multiply Eq.(4.8) by $w_t - g_t(x, t)$ and then integrate over Q_T . Using the assumption H(4.1) and the growth condition for $\sigma(x, t, u)$, we obtain, after some routine calculations, that

$$\begin{aligned} & \sup_{0 \leq t \leq T} \int_0^1 [w_t^2 + w_x^2] dx + \int_0^T \int_0^1 \sigma(x, t, u) w_t^2 dx dt \\ & \leq C_1 + C_2 \int_0^T \int_0^1 |u| dx dt, \end{aligned}$$

where the constants C_1 and C_2 depend only on known data, but not on n .

On the other hand, we use an estimate from the paper [3] to obtain

$$\int_0^1 |u| dx \leq C_2 + C_4 \int_0^T \int_0^1 \sigma(x, t, u) |w_t|^2 dx dt,$$

where the constants C_3 and C_4 depend only on known data.

It follows that

$$\int_0^1 |u| dx \leq C_3 + C_4 [C_1 + C_2 \int_0^T \int_0^1 |u| dx dt].$$

The above estimate holds if we replace T by any $T' \in [0, T]$, we can apply Gronwall's inequality to obtain

$$\int_0^1 |u| dx \leq C_5,$$

where C_5 depends only on known data.

Next, we multiply Eq. (4.9) by u and then integrate over $Q_{T'}$ with $T' \in (0, T]$. Using the same technique as in Section 2, we see

$$\begin{aligned} & \int \int_{Q_{T'}} A_n(x, u)_t u dx dt \geq b_0 \int_{\Omega} u^2 dx - C_6, \\ & \int \int_{Q_{T'}} u_{xx} u dx dt = - \int \int_{Q_{T'}} u_x^2 dx dt \end{aligned}$$

where $b_0 > 0$ and C_6 depend only on known data.

It follows that

$$\begin{aligned} \int_0^1 u^2(x, T') dx + \int_0^{T'} \int_0^1 u_x^2 dx dt &\leq C + \int_0^T \int_0^1 |u| \sigma(x, t, u) w_t^2 dx dt \\ &\leq C + C \int_0^T \|u\|_{L^\infty(0,1)}^2 dt. \end{aligned}$$

Now, by Sobolev's embedding ([10]),

$$\begin{aligned} \|u\|_{L^\infty(0,1)}^2 &\leq C \|u\|_{W^{1,2}(0,1)} \|u\|_{L^2(0,1)} \\ &\leq \delta \int_0^1 [u^2 + u_x^2] dx + C(\delta) \int_0^1 u^2 dx. \end{aligned}$$

We combine the above estimates and choose δ sufficiently small to obtain

$$\int_0^1 u^2 dx + \int_0^{T'} \int_0^1 u_x^2 dx dt \leq C + C \int_0^{T'} \int_0^1 u^2 dx dt.$$

Again Gronwall's inequality yields

$$\int_0^1 u^2 dx + \int_0^{T'} \int_0^1 u_x^2 dx dt \leq C_8,$$

where the constant C_8 depends only on known data.

With those uniform estimates, as for Theorem 2.4 we can extract a subsequence from $(w_n(x, t), u_n(x, t))$ and then take the limit to obtain a weak solution to the problem (4.4)-(4.7). We shall not repeat these steps here.

Q.E.D.

Remark 4.1: It would be interesting to show that the temperature is continuous over Q_T (see [1, 4]).

Remark 4.2: The uniqueness is an open question even for one-space dimension.

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